## $18.022\ 2014,\ \mathrm{Midterm}\ \mathrm{Exam}\ 2$

Please explain all your work. You have 50 minutes. Allowed materials are the lecture notes only.

Name:

Signature:

Student ID:

Recitation leader:

Recitation number and time: \_\_\_\_

Question	Score
1a	
1b	
2a	
2b	
2c	
2d	
2e	
2f	
3a	
3b	
Total	

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(1) (22 points) Let  $f : \mathbb{R} \to \mathbb{R}$  be given by  $f(x) = e^{-x}$ , and suppose that  $\vec{a} \in \mathbb{R}^3$  is constant. Define  $T : \mathbb{R}^3 \to \mathbb{R}$  by

$$T(\vec{x}) = f(|\vec{x} - \vec{a}|^2) = e^{-|\vec{x} - \vec{a}|^2}.$$

We may think of  $T(\vec{x})$  as the temperature at  $\vec{x} \in \mathbb{R}^3$  resulting from a heat source at  $\vec{a}$ ; note that the temperature only depends on the distance from  $\vec{x}$  to  $\vec{a}$ .

- (a) Calculate  $\nabla T(\vec{x})$  at a point  $\vec{x} \in \mathbb{R}^3$ .
- (b) Recall that if  $\hat{n}$  is a unit vector, then the directional derivative of T in the direction  $\hat{n}$  at  $\vec{x} \in \mathbb{R}^3$  is given by

$$D_{\hat{n}}T(\vec{x}) = \lim_{h \to 0} \frac{T(\vec{x} + h\hat{n}) - T(\vec{x})}{h}$$

Fix a point  $\vec{x} \in \mathbb{R}^3$ . For which unit vectors  $\hat{n}$  is  $D_{\hat{n}}T(\vec{x})$  equal to zero? (i.e., in which directions does the temperature not change?). Give a short geometric interpretation of your answer.

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(2) (56 points) Suppose  $\vec{x} : \mathbb{R} \to \mathbb{R}^2$  is a regular curve of class  $\mathcal{C}^2$ , parametrized by arclength (so that  $|\vec{x}'(t)| = 1$ ). Let  $\lambda > 0$  and  $\theta \in \mathbb{R}$  be constants, let

$$M = \begin{pmatrix} \lambda \cos \theta & -\lambda \sin \theta \\ \lambda \sin \theta & \lambda \cos \theta \end{pmatrix},$$

and let  $g: \mathbb{R}^2 \to \mathbb{R}^2$  be given by  $g(\vec{x}) = M\vec{x}$ . Let  $\vec{r}: \mathbb{R} \to \mathbb{R}^2$  be given by  $\vec{r}(t) = g(\vec{x}(t))$ .

- (a) Let  $\vec{v} \in \mathbb{R}^2$  be a non-zero vector. Show that  $|g(\vec{v})|$ , the norm of  $g(\vec{v})$ , is equal to  $\lambda |\vec{v}|$ , and that the angle between  $\vec{v}$  and  $g(\vec{v})$  is  $\theta$ .
- (b) Calculate the partial derivatives of  $g\left(\frac{\partial g_i}{\partial x_j}\right)$  for i = 1, 2 and j = 1, 2, and explain why g is differentiable. What is the matrix Dg (that is, the derivative of g)?

(c) Calculate  $\vec{r}'(t)$  in terms of  $\vec{x}'(t)$ . (Hint: use the chain rule.)

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(d) Calculate  $s_r(t)$ , the arclength parametrization of  $\vec{r}$ , with respect to the reference point t = 0 (this is the distance along the curve  $\vec{r}$  from 0 to t). (Hint: Recall that  $\vec{x}(t)$  is parametrized by arclength. Calculate  $s'_r(t)$  and then integrate.)

- (e) Calculate  $\vec{T}_r(t)$ , the unit tangent vector of  $\vec{r}$ , in terms of  $\vec{T}_x(t)$ , the unit tangent vector of  $\vec{x}$ .
- (f) **Extra credit:** Calculate  $\vec{N}_r(t)$ , the unit normal vector of  $\vec{r}$  as well as  $\kappa_r(t)$ , the curvature of  $\vec{r}$ , in terms of  $\vec{N}_x(t)$  and  $\kappa_x(t)$ , the unit normal vector of  $\vec{x}$  and the curvature of  $\vec{x}$ .

(3) (22 points) Given an  $f: \mathbb{R}^n \to \mathbb{R}$  of class  $\mathcal{C}^2$ , recall that the Hessian Matrix  $H = (h_{ij})$  is the *n*-by-*n* matrix given by

$$h_{ij} = \frac{\partial^2 f}{\partial x_i \partial x_j}.$$

Suppose  $M = (m_{ij})$  is a symmetric  $2 \times 2$  matrix (i.e.,  $m_{ij} = m_{ji}$ ), suppose  $\vec{a} \in \mathbb{R}^2$ , and let  $f : \mathbb{R}^2 \to \mathbb{R}$  be given by

$$f(\vec{x}) = \vec{a} \cdot \vec{x} + \frac{1}{2}\vec{x} \cdot (M\vec{x}).$$

This can also be written as

$$f(x_1, x_2) = a_1 x_1 + a_2 x_2 + \frac{1}{2} (x_1 m_{11} x_1 + x_1 m_{12} x_2 + x_2 m_{21} x_1 + x_2 m_{22} x_2).$$

Note that  $(a_i)$  and  $(m_{ij})$  are constants.

- (a) Show that the gradient of f at  $\vec{x} \in \mathbb{R}^2$  is equal to  $\vec{a} + M\vec{x}$ , and calculate f's Hessian.
- (b) Assume now that det  $M \neq 0$ , so that M is invertible. Solve the equation  $\nabla f(p) = \vec{0}$ , and calculate the tangent plane to the graph of f at the solution p, in terms of f(p).